An Introduction to the Deformation Theory of Complete Intersection Singularities

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March 18, 2021

Brief introductory note because I got lazy: analytic spaces

■ A finite-type C-scheme is a locally ringed space which is locally isomorphic to the vanishing of some ideal of Aⁿ_C, where Aⁿ_C has the Zariski topology and O_{Aⁿ_C} is the sheaf of polynomials.

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- An analytic space is a locally ringed space which is locally isomorphic to the vanishing of some ideal of Cⁿ, where Cⁿ has the classical topology and O_{Cⁿ} is the sheaf of holomorphic functions.

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- An analytic space is a locally ringed space which is locally isomorphic to the vanishing of some ideal of Cⁿ, where Cⁿ has the classical topology and O_{Cⁿ} is the sheaf of holomorphic functions.
- We'll use the latter setup in this talk because there were things I didn't get around to verifying in the algebraic setting; if it makes you uncomfortable and you like to live dangerously you can try ignoring it and just thinking about polynomials.

Deformations in general

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- Often we want to look at a map \(\phi : X \rightarrow S\) as giving us a family of subspaces of X indexed by points of S.
- To make sure that the fibers vary nicely as we look at different points in the base, we require that φ be flat which is to say that all the corresponding maps of local rings O_{S,φ(x)} → O_{X,x} are flat.
- We can now ask questions about how the fibers relate to each other, what kind of deformations of a certain space are possible, etc.

We'll look at map germs

$$F: (\mathbb{C}^{n+k}, 0) \to (\mathbb{C}^k, 0);$$

these are given by a choice of k coordinate functions defined and holomorphic in a neighborhood of the origin in \mathbb{C}^{n+k} . For convenience, we'll write X for the source and S for the target.

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• Let X_0 be the fiber over the origin; we'll require that it have dimension n, so that it's (the germ of) a complete intersection in \mathbb{C}^{n+k} (since $\mathcal{O}_{X,0}$ is Cohen-Macaulay and $\mathcal{O}_{S,0}$ is regular, this means F is flat).

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- We'll call F a deformation of the complete intersection singularity (X₀, 0).

Aside: The Milnor fiber

The general fiber of F, which is smooth, is called its Milnor fiber.

- Some people care about how its topology relates to the singularities of (X₀, 0).
- A simpler question: Is it obvious whether it's even an invariant of (X₀, 0)? That is, could it depend on F?

Is there a universal deformation?

• If $F: (X,0) \to (S,0)$ is a deformation of $(X_0,0)$ and $g: (S',0) \to (S,0)$ (for $S' = \mathbb{C}^{k'}$) is a nice enough map, we get another deformation via pullback:

$$\begin{array}{ccc} (X',0) & \stackrel{\tilde{g}}{\longrightarrow} (X,0) \\ F' & F \\ (S',0) & \stackrel{g}{\longrightarrow} (S,0) \end{array}$$

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- We can ask whether there is a deformation of (X₀, 0) universal in the sense that every other deformation can be written uniquely as a pullback from it.
- Answer: Only if $(X_0, 0)$ is smooth (i.e., extremely boring).

Is there a versal deformation?

Being versal is like being universal without the uniqueness we ask only if there's a deformation of (X₀, 0) such that we can get all others as pullbacks, maybe non-uniquely.

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- Being versal is like being universal without the uniqueness we ask only if there's a deformation of (X₀, 0) such that we can get all others as pullbacks, maybe non-uniquely.
- This still seems like a pretty miraculous thing to ask for, but it turns out that such deformations do exist if (X₀, 0) has only an isolated singularity at the origin (i.e., X₀ \ {0} is smooth this implies that all nearby fibers have at worst isolated singularities as well).

Preliminary stuff about vector fields

• Let $\mathcal{T}_{X,0}$ denote the $\mathcal{O}_{X,0}$ -module of germs of holomorphic vector fields on X (and define $\mathcal{T}_{S,0}$ similarly). Concretely, $\mathcal{T}_{X,0} = \mathcal{O}_{X,0} \frac{\partial}{\partial x_1} \oplus \ldots \oplus \mathcal{O}_{X,0} \frac{\partial}{\partial x_{n+k}}$.

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- Then $F^*\mathcal{T}_{5,0} = \mathcal{O}_{X,0} \otimes_{\mathcal{O}_{5,0}} \mathcal{T}_{5,0} = \mathcal{O}_{X,0} \frac{\partial}{\partial t_1} \oplus \ldots \oplus \mathcal{O}_{X,0} \frac{\partial}{\partial t_k}$ corresponds to a (holomorphic) choice at each point of X of a tangent vector to S.

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- We can view the derivative of F as a map $dF : \mathcal{T}_{X,0} \to F^*\mathcal{T}_{S,0}$.

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Toward the Kodaira-Spencer map

• Set
$$T^1_{X/S,0} = \operatorname{coker}(dF) (= \operatorname{Ext}^1_{\mathcal{O}_{X,0}}(\Omega_{X/S,0}, \mathcal{O}_{X,0}))$$
 and
 $T^1_{X_{0,0}} = T^1_{X/S,0}/(F_1, \dots, F_k)T^1_{X/S,0}$
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Intuition: T¹_{X/S,0} gives us a choice for each point in X of a way to move in S that will actually deform X at S in a nontrivial way (this is why we mod out by dF). T¹_{X0,0} is just the restriction to X₀.

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- Since $T^1_{X_{0,0}}$ is independent of *F*, we can think of it as "the vector space of all possible ways to deform X_0 ".

The Kodaira-Spencer map

The natural map

$$\rho_{F,0}: \mathcal{T}_{S,0} \to \mathcal{T}^1_{X/S,0}$$

is called the Kodaira-Spencer map. Its restriction

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to the tangent space of S at the origin is the **reduced Kodaira-Spencer map**.

 Fact: A deformation of (X₀,0) is versal if and only if its (reduced) Kodaira-Spencer map is surjective.

Existence of versal deformations in the isolated case

• Notice that $T^1_{X/S,0} = \operatorname{coker}(dF)$, by definition, is supported only on the critical locus of F (i.e., the locus where the Jacobian drops rank and hence dF is not surjective).

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- Hence $T_{X_0,0}^1$ is supported only on the singular locus of X_0 , so it's finite-dimensional if X_0 has an isolated singularity at the origin.

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- Hence $T_{X_0,0}^1$ is supported only on the singular locus of X_0 , so it's finite-dimensional if X_0 has an isolated singularity at the origin.
- We can use this to extend F in a straightforward way and get a versal deformation.

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• Let
$$F: (\mathbb{C}^2, 0) \to (\mathbb{C}, 0)$$
 be given by $F(x, y) = y^2 - x^3$.

• Hence
$$T^1_{X/S,0} = (\mathbb{C}\{\{x,y\}\}/(x^2,y))\frac{\partial}{\partial t} = (\mathbb{C}[x]/(x^2))\frac{\partial}{\partial t}$$

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- Let F: (C², 0) → (C, 0) be given by F(x, y) = y² x³.
 Then T_{X,0} = C{{x, y}} ∂/∂x ⊕ C{{x, y}} ∂/∂y, F*T_{S,0} = C{{x, y}} ∂/∂t, and dF takes ∂/∂x to -3x²∂/∂t and ∂/∂y to 2y∂/∂t.
 Hence T¹_{X/S,0} = (C{{x, y}}/(x², y))∂/∂t = (C[x]/(x²))∂/∂t, T¹_{X0,0} = T¹_{X/S,0}/(y² - x³)T¹_{X/S,0} = T¹_{X/S,0}, and the reduced Kodaira-Spencer map C∂/∂t → (C[x]/(x²))∂/∂t is given by ∂/∂t → ∂/∂t.
- Now we can build a versal deformation *F* : (ℂ³, 0) → (ℂ², 0) by *F*(*x*, *y*, *u*) = (*y*² − *x*³ + *ux*, *u*).

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Questions?

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Check out Looijenga's Isolated Singular Points on Complete Intersections!