

(Differential) Worksheet 5: Manifolds

2023 Geometry/Topology SEP, UW-Madison

July 31

1. (Question 6, Summer 2020) Prove that any smooth map from a 2-dimensional manifold M to the standard sphere S^3 is homotopic to a constant map.

(The following statements may be useful, not useful, or wrong: 1. Any continuous map from M to \mathbb{R}^3 is homotopic to a constant map. 2. There is a theorem which holds for smooth maps but not for continuous maps.)

2. (Question 5, Winter 2018) Let $\Phi : \mathbb{R}^2 \rightarrow \mathbb{R}$ defined by $\Phi(x, y) = x^2 - y^2$.
 - (a) Show that $\Phi^{-1}(0)$ is **not** an embedded submanifold of \mathbb{R}^2 .
 - (b) Can $\Phi^{-1}(0)$ be given a topology and smooth structure making it into an immersed submanifold of \mathbb{R}^2 ?

3. (Question 5, Summer 2017) Let S^n be the unit n -sphere.
 - (a) Prove that the tangent bundle TS^3 is diffeomorphic to $S^3 \times \mathbb{R}^3$.
 - (b) For any n , is the tangent bundle TS^n always diffeomorphic to $S^n \times \mathbb{R}^n$? Please justify your answers.

4. (Question 5, Winter 2017) Recall that $2n \times 2n$ real matrices can be identified with the points of \mathbb{R}^{4n^2} in an obvious manner. Thus the set of all nonsingular $2n \times 2n$ real matrices, denoted by $GL(2n, \mathbb{R})$, has a natural manifold structure as the open subset of \mathbb{R}^{4n^2} where the determinant function does not vanish.

Consider the set

$$\mathrm{Sp}(2n, \mathbb{R}) = \{A \in GL(2n, \mathbb{R}) : A^T \Omega A = \Omega\},$$

where A^T is the transpose of the matrix A and

$$\Omega = \begin{bmatrix} 0 & I_n \\ -I_n & 0 \end{bmatrix}$$

with I_n the $n \times n$ identity matrix. Prove that $\mathrm{Sp}(2n, \mathbb{R})$ has a manifold structure in which the inclusion map $i : \mathrm{Sp}(2n, \mathbb{R}) \hookrightarrow \mathrm{GL}(2n, \mathbb{R})$ is a smooth imbedding.

5. (Question 4, Winter 2018) Let M be a non-empty topological n -manifold without boundary with $n \geq 1$. If M has a smooth structure, show that M has uncountably many smooth structures.
6. (Question 4, Summer 2017) The n -dimensional real projective space, denoted by \mathbb{RP}^n , is defined as the set of 1-dimensional linear subspaces of the Euclidean $(n + 1)$ -space \mathbb{R}^{n+1} . We give it the quotient topology given by the map $\pi : \mathbb{R}^{n+1} \setminus \{0\} \rightarrow \mathbb{RP}^n$ sending $x \in \mathbb{R}^{n+1} \setminus \{0\}$ to the line through x and 0. Show that \mathbb{RP}^n has a smooth manifold structure.